## Functions of a Complex Variable

## FUNCTIONS

If to each of a set of complex numbers which a variable $z$ may assume there corresponds one or more values of a variable $w$, then $w$ is called a function of the complex variable $z$, written $w=f(z)$.

A function is single-valued if for each value of $z$ there is only one value of $w$; otherwise it is multiple-valued or manyvalued. In general we can write $w=f(z)=$ $u(x, y)+i v(x, y)$, where $u$ and $v$ are real functions of $x$ and $y$.

Example 1:
$w=z^{2}=(x+i y)^{2}=x^{2}-y^{2}+2 i x y$ so that
$u(x, y)=x^{2}-y^{2}, v(x, y)=2 x y$. These are
called real and imaginary parts of $w=z^{2}$ respectively.
Unless otherwise specified we shall assume that $f(z)$ is single-valued. A function, which is multiple-valued, can be considered as a collection of single-valued functions.

## LIMITS AND CONTINUITY

Definitions of limits and continuity for functions of a complex variable are similar to those for a real variable. Thus, $f(z)$ is said to have the limit $l$ as $z$ approaches $z_{0}$, if given any $\varepsilon>0$, there exist a $\delta>0$, such that $|f(z)-l|<\varepsilon$ whenever $0<z-z_{0} \mid<\delta$.

Similarly, $f(z)$ is said to be continuous at $z_{0}$ if, given any $\varepsilon>0$, there exist a $\delta>0$, such that $\mid f(z)-f\left(z_{0}\right)<\varepsilon$ when $\left|z-z_{0}\right|<\delta$. Alternatively, $f(z)$ is continuous at $z_{0}$ if $\lim f(z)=f\left(z_{0}\right)$.
$z \rightarrow z_{0}$

## Theorems on limits

If $\lim _{z \rightarrow z_{0}} f(z)=A$ and $\lim _{z \rightarrow z_{0}} g(z)=B$, then

1. $\lim _{z \rightarrow z_{0}}\{f(z)+g(z)\}=A+B$
2. $\lim _{z \rightarrow z_{0}}\{f(z)-g(z)\}=A-B$
3. $\lim _{z \rightarrow z_{0}}\{f(z) g(z)\}=A B$
4. $\lim _{z \rightarrow z_{0}}\{f(z) / g(z)\}=A / B$ if $B \neq 0$

## DERIVATIVES

If $f(z)$ is single-valued in some region of the $z$ plane the derivative of $f(z)$, denoted by $f^{\prime}(z)$, is defined as

$$
\begin{equation*}
\lim _{\Delta z \rightarrow 0} \frac{f(z+\Delta z)-f(z)}{\Delta z} \tag{1}
\end{equation*}
$$

provided the limit exists independent of the manner in which $\Delta z \rightarrow 0$. If this limit exists for $z=z_{0}$, then $f(z)$ is called analytic at $z_{0}$. If the limit (1) exists for all $z$ in a region $R$, then $f(z)$ is called analytic in $\boldsymbol{R}$. In order to be analytic $f(z)$ must be single-valued and continuous. The converse, however, is not necessarily true.

We define elementary functions of a complex variable by a natural extension of the corresponding functions of a real variable. Where series expansions for real functions $f(x)$ exist, we can use as definitions the series with $x$ replaced by $z$.
Example 2: We define

$$
\begin{aligned}
& e^{z}=1+z+\frac{z^{2}}{2!}+\frac{z^{3}}{3!}+\cdots \\
& \sin (z)=z-\frac{z^{3}}{3!}+\frac{z^{5}}{5!}-\frac{z^{7}}{7!}+\cdots \\
& \cos (z)=1-\frac{z^{2}}{2!}+\frac{z^{4}}{4!}-\frac{z^{6}}{6!}+\cdots
\end{aligned}
$$

From these we can show that $e^{z}=e^{x+i y}=$ $e^{x}(\cos y+i \sin y)$, as well as many other relations.

## Example 3:

We define $d^{b}$ as $e^{b l n} a$ even when $a$ and $b$ are complex numbers. Since $e^{2 k \pi i}=1$, it follows that $e^{i \phi}=e^{i(\phi+2 k \pi)}$ and we define

$$
\ln z=\ln \left(\rho e^{i \phi}\right)=\ln \rho+i(\phi+2 k \pi)
$$

Thus $\ln z$ is a many-valued function. The various single-valued functions of which this many-valued function is composed are called its branches.

Rules for differentiating functions of a complex variable are much the same as for those of real variables. Thus

$$
\begin{aligned}
& \frac{d}{d z}\left(z^{n}\right)=n z^{n-1} \\
& \frac{d}{d z}\left(e^{z}\right)=e^{z} \\
& \frac{d}{d z}(\sin z)=\cos z \\
& \frac{d}{d z}(\cos z)=-\sin z,
\end{aligned}
$$

etc.

## CAUCHY-RIEMANN EQUATIONS

A necessary condition, that $w=f(z)=$ $u(x, y)+i v(x, y)$ be analytic in a region $\boldsymbol{R}$ is that $u$ and $v$ satisfy the Cauchy-Riemann equations

$$
\begin{equation*}
\frac{\partial u}{\partial x}=\frac{\partial v}{\partial y}, \quad \frac{\partial u}{\partial y}=-\frac{\partial v}{\partial x} . \tag{2}
\end{equation*}
$$

This condition is easy to prove first choosing $\Delta y=0$ (thus $\Delta z=\Delta x$ ), then choosing $\Delta x=0$ (thus $\Delta z=i \Delta y$ ), and finally equating the expressions for the derivatives of $f(z)$ obtained in these two cases. If the partial derivatives in (2) are continuous in $\boldsymbol{R}$, the equations are sufficient conditions that $f(z)$ be analytic in $\boldsymbol{R}$.

If the second derivatives of $u$ and $v$ with respect to $x$ and $y$ exist and are continuous, we find by differentiating (2) that

$$
\begin{equation*}
\frac{\partial^{2} u}{\partial x^{2}}+\frac{\partial^{2} u}{\partial y^{2}}=0, \quad \frac{\partial^{2} v}{\partial x^{2}}+\frac{\partial^{2} v}{\partial y^{2}}=0 \tag{3}
\end{equation*}
$$

Thus $u$ and $v$ satisfy Laplace's equation in 2 dimensions. Functions satisfying Laplace's equation are called harmonic functions.

## INTEGRALS

If $f(z)$ is single-valued and continuous in a region $\boldsymbol{R}$ we define the integral of $f(z)$ along some path $C$ in $\boldsymbol{R}$ from point $z_{1}$ to point $z_{2}$, where $z_{1}=x_{1}+i y_{1}, z_{2}=x_{2}+i y_{2}$, as

$$
\begin{array}{r}
\int_{C} f(z) d z=\int_{\left(\left(_{1}+i y_{1}\right)\right.}^{\left(x_{2}+i y_{2}\right)}(u+i v)(d x+i d y)= \\
\int_{\left(x_{1}+i y_{1}\right)}^{\left(x_{2}+i y_{2}\right)} u d x-v d y+i \int_{\left(x_{1}+i y_{1}\right)}^{\left(x_{2}+i y_{2}\right)} v d x+u d y \tag{4}
\end{array}
$$

with this definition the integral of a function of a complex variable can be made to depend on line integrals for real functions already considered in Math-2 (see, e.g. Chapter 6 of Spiegel's textbook). An alternative definition based on the limit of a sum, as for functions of a real variable, can also be formulated and turns out to be equivalent to the one above.

The rules for complex integration are similar to those for real integrals. An important result is

$$
\left|\int_{C} f(z) \mathrm{dz}\right| \leq \int_{C}|f(z)| d z \mid \leq M \int_{C} d s=M L .
$$

Here $M$ is the upper bound of $\mid f(z)$ on $C$, i.e. $|f(z)| \leq M$, and $L$ is the length of the path $C$.

## CAUCHY'S THEOREM

Let $C$ be a simple closed curve. If $f(z)$ is analytic within the region bounded by $C$ as well as on C, then we have Cauchy's theorem that

$$
\begin{equation*}
\int_{C} f(z) d z=\oint_{C} f(z) d z=0, \tag{5}
\end{equation*}
$$

where the second integral emphasises the fact that $C$ is a simple closed curve.

Expressed in another way, equation (5) is equivalent to the statement that $\int_{z_{1}}^{z_{2}} f(z) d z$ has a value independent of the path joining $z_{1}$ and $z_{2}$. Such integrals can be evaluated as $F\left(z_{2}\right)-F\left(z_{1}\right)$ where $F^{\prime}(z)=f(z)$.

The proof of Cauchy's theorem follows immediately from Eq. (4), Cauchy-Riemann equations (3) and Green's theorem in the plane (see Math-2 or Chapter 6 of Spiegel):

$$
\oint_{c}(P \mathrm{~d} x+Q \mathrm{~d} y)=\iint_{R}\left(\frac{\partial Q}{\partial x}-\frac{\partial P}{\partial y}\right) \mathrm{d} x \mathrm{~d} y .
$$

Example 4: Since $f(z)=z$ is analytic everywhere

$$
\oint_{C} z \mathrm{~d} z=0 . \quad \text { Also, } \quad \int_{2 i}^{1+i} z \mathrm{~d} z=\left.\frac{z^{2}}{2}\right|_{2 i} ^{1+i}=i+2
$$

## CAUCHY'S INTEGRAL FORMULAS

If $f(z)$ is analytic within and on a simple closed curve $C$ and $a$ is any point interior to $C$, then

$$
\begin{equation*}
f(a)=\frac{1}{2 \pi i} \oint_{C} \frac{f(z)}{z-a} \mathrm{~d} z, \tag{6}
\end{equation*}
$$

where $C$ is traversed in the positive (counterclockwise) sense.

Also, the $n$th derivative of $f(z)$ at $z=c$ is given by

$$
\begin{equation*}
f^{(n)}(a)=\frac{n!}{2 \pi i} \oint_{C} \frac{f(z)}{(z-a)^{n+1}} \mathrm{~d} z . \tag{7}
\end{equation*}
$$

Equations (6) and (7) are called Cauchy's integral formulas. They are quite remarkable because they show that if the function $f(z)$ is known on the closed curve $C$ then it is also known within $C$, and the various derivatives at points within $C$ can be calculated. Thus if a function of a complex variable has a first derivative, it has all higher derivatives as well. This of course is not necessarily true for functions of real variables.

## TAYLOR'S SERIES

Let $f(z)$ be analytic inside and on a circle having its centre at $z=a$. Then for all points $z$ in the circle we have the Taylor series representation of $f(z)$ given by
$f(z)=f(a)+f^{\prime}(a)(z-a)+\frac{f^{\prime \prime}(a)}{2!}(z-a)^{2}+\cdots$

## SINGULAR POINTS

A singular point of a function $f(z)$ is a value of $z$ at which $f(z)$ fails to be analytic. If $f(z)$ is analytic everywhere in some region except at interior except at an interior point $z=a$, we call $z=a$ an isolated singularity of $f(z)$.

Example 5: If $f(z)=\frac{1}{(z-5)^{3}}$, then $z=5$ is an isolated singularity of $f(z)$.

## POLES

$$
\text { If } f(z)=\frac{\phi(z)}{(z-a)^{n}}, \phi(a) \neq 0 \text {, where } \phi(z) \text { is }
$$

analytic everywhere in the region including $z=a$, and if $n$ is a positive integer, then $f(z)$ has an isolated singularity at $z=a$ which is called a pole of order $n$. If $n=1$, the pole is often called a simple pole; if $n=2$ it is called a double pole, etc.

Example 6:

$$
f(z)=\frac{z^{3}}{(z-5)^{2}(z+2)}
$$

has two singularities: a pole of the order 2 or double pole at $z=5$, and a pole of order 1 or simple pole at $z=-2$.

A function can have other types of singularities besides poles. For example $f(z)=\sqrt{z}$ has a branch point at $z=0$. The function $f(z)=\frac{\sin z}{z}$ has a singularity at $z=0$. $z$
However, since $\lim _{z \rightarrow 0} \frac{\sin z}{z}$ is finite, we call such a singularity removable singularity.

## LAURENT SERIES

If $f(z)$ has a pole of order $n$ at $z=a$ but is analytic at every other point inside and on a circle $C$ with centre at $a$, then $(z-a)^{n} f(z)$ is analytic at all points inside and on $C$ and has a Taylor series about $z=a$ so that

$$
\begin{align*}
f(z)= & \frac{a_{-n}}{(z-a)^{n}}+\frac{a_{-n+1}}{(z-a)^{n-1}}+\cdots+\frac{a_{-1}}{z-a}+  \tag{9}\\
& +a_{0}+a_{1}(z-a)+a_{2}(z-a)^{2}+\cdots
\end{align*}
$$

This is called a Laurent series for $f(z)$. The part $a_{0}+a_{1}(z-a)+a_{2}(z-a)^{2}+\cdots$ is called the analytic part, while the remainder consisting of inverse powers of $z-a$ is called the principal part. More generally, we refer to the series $\sum_{k=-\infty}^{\infty} a_{k}(z-a)^{k}$ as a Laurent series where the terms with $k<0$ constitute the principal part. A function which is analytic in a region bounded by two concentric circles having centre at $z=a$ can always be expanded in such a Laurent series.

It is possible to define various types of singularities of a function $f(z)$ from its Laurent series. For example, when the principal part of a Laurent series has a finite number of terms and $a_{-n} \neq 0$ while $a_{-n-1}$, $a_{-n-2}, \ldots$ are all zero, then $z=a$ is a pole of order $n$. If the principal part has infinitely many terms, $z=a$ is called an essential singularity or sometimes a pole of infinite order.

## Example 7:

The function $\exp (1 / z)=1+\frac{1}{z}+\frac{1}{2!z^{2}}+\cdots$ has an essential singularity at $z=0$.

## RESIDUES

The coefficients in (9) can be obtained by writing the coefficients for the Taylor series corresponding to $(z-a)^{n} f(z)$. The coefficient $a_{-1}$, called the residue of $f(z)$ at the pole $z=a$, is of considerable importance. It can be found from the formula

$$
\begin{equation*}
a_{-1}=\lim _{z \rightarrow a} \frac{1}{(n-1)!} \frac{\mathrm{d}^{n-1}}{\mathrm{~d} z^{n-1}}\left\{(z-a)^{n} f(z)\right\} \tag{10}
\end{equation*}
$$

where $n$ is the order of the pole. For simple poles the calculation of the residue is of particular simplicity since it reduces to

$$
\begin{equation*}
a_{-1}=\lim _{z \rightarrow a}(z-a) f(z) \tag{11}
\end{equation*}
$$

Example 8: If $f(z)=\frac{1}{z(z-2)^{2}}$, then $z=0$ is a simple pole, $z=2$ is a pole of order 2. Thus:
Residue at $z=0$ is $\lim _{z \rightarrow 0} z \cdot \frac{1}{z(z-2)^{2}}=\frac{1}{4}$.
Residue at $z=2$ is
$\lim _{z \rightarrow 2} \frac{d}{d z}\left\{(z-2)^{2} \cdot \frac{1}{z(z-2)^{2}}\right\}=-\frac{1}{4}$.

## RESIDUE THEOREM

If $f(z)$ is analytic in a region $\boldsymbol{R}$ except for a pole of order $n$ at $z=a$ and if $C$ is any simple closed curve in $\boldsymbol{R}$ containing $z=a$, then $f(z)$ has the form (9) (Laurent series). Integrating (9), and using the fact that

$$
\oint_{c} \frac{\mathrm{~d} z}{(z-a)^{n}}= \begin{cases}2 \pi i & \text { if } n=1  \tag{12}\\ 0 & \text { if } n=2,3,4, \ldots\end{cases}
$$

(see Problem 1.7), it follows that

$$
\begin{equation*}
\oint_{c} f(z) \mathrm{d} z=2 \pi i a_{-1} \tag{13}
\end{equation*}
$$

i.e. the integral of $f(z)$ around a closed path enclosing a single pole of $f(z)$ is $2 \pi i$ times the residue at the pole.

More generally, we have the following Theorem 1: If $f(z)$ is analytic within and on the boundary $C$ of a region $\boldsymbol{R}$ except at a finite number of poles $a, b, c, \ldots$ within $R$, having residues $a_{-1}, b_{-1}, c_{-1}, \ldots$ respectively, then

$$
\begin{equation*}
\oint_{c} f(z) \mathrm{d} z=2 \pi i\left(a_{-1}+b_{-1}+c_{-1}+\cdots\right) \tag{14}
\end{equation*}
$$

Cauchy's theorem and integral formula are special cases of this result, which we call the residue theorem.

## EVALUATION OF DEFINITE INTEGRALS

The evaluation of various real definite integrals can often be achieved by using the residue theorem together with a suitable function $f(z)$ and a suitable path or contour $C$, the choice of which may require great ingenuity. The following types are most common in practice.

1. $\int_{0}^{\infty} F(x) \mathrm{d} x, F(x)$ is an even function.

Consider $\oint_{C} F(z) \mathrm{d} z$ along a contour $C$ consisting of the line along the $x$ axis from $-R$ to $+R$ and the semi-circle above the $x$ axis having this line as diameter. Then let $R \rightarrow \infty$.
2. $\int_{0}^{2 \pi} G(\sin \theta, \cos \theta) \mathrm{d} \theta, G$ is a rational function of $\sin \theta$ and $\cos \theta$.
Let $z=e^{i \theta}$. Then $\sin \theta=\frac{z-z^{-1}}{2 i}, \cos \theta=\frac{z+z^{-1}}{2}$ and $\mathrm{d} z=i e^{i \theta} \mathrm{~d} \theta$ or $\mathrm{d} \theta=\mathrm{d} z / i z$. The integral is equivalent to $\oint_{C} F(z) \mathrm{d} z$ where $C$ is the unit circle with center at the origin.
3. $\int_{-\infty}^{\infty} F(x)\left\{\begin{array}{l}\cos (m x) \\ \sin (m x)\end{array}\right\} d x, F(x)$ is a
rational function.
Here we consider $\int_{C} F(z) e^{i m z} d z$ where
$C$ is the same contour as that in Type 1.
4. Miscellaneous integrals involving particular contours. See Problems.

Useful property of contour integrals:
If $\left\lvert\, f(z) \leq \frac{M}{R^{k}}\right.$ for $z=R e^{i \theta}$, where $k>1$ and
$M$ are constants, then $\lim _{R \rightarrow \infty} \int_{\Gamma} f(z) d z=0$ where $\Gamma$ is the semi-circular arc of radius $R$ above the $x$ axis.

Proof:
By the result at the bottom of page 7, we have
$\left|\int_{\Gamma} f(z) \mathrm{dz}\right| \leq \int_{\Gamma}|f(z)| \mathrm{d} z \left\lvert\, \leq \frac{M}{R^{k}} \pi R=\frac{\pi M}{R^{k-1}}\right.$
since the length of arc $L=\pi R$. Then $\lim _{R \rightarrow \infty} \int_{\Gamma} f(z) \mathrm{dz} \mid=0$ and so $\lim _{R \rightarrow \infty} \int_{\Gamma} f(z) \mathrm{dz}=0$.

